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**Notes:**

1. Untranslatable words are replaced with asterisks (\*\*\*).
2. Texts in the figures are not translated and shown as it is.

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## DESCRIPTION OF DRAWINGS

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### [Brief Description of the Drawings]

[Drawing 1] The exploded perspective view of an important section showing one work example of this invention

[Drawing 2] It is for explaining a positioning function, and as for (a), it is the front view of a positioning preparatory step, and (b) is a front view in a positioning state.

[Drawing 3] The sectional view of the important section shown according to a positioning state

[Drawing 4] The sectional view of the joining segment of a lower arm and an upper arm

[Drawing 5] The whole robot's side view

### [Explanations of letters or numerals]

A base and 3 among drawing a body and 4 a lower arm and 5 for two An upper arm (support side), As for a wrist and 8, a motor and 11 for 6 housing and 10 a twist arm and 7 A reduction gear, A crank part and 14 press down an output axis and 13, 12 presses down a connection part and 17 a cross roller bearing and 18, and, as for a tapped hole (attachment) and 25, housing and 21 are [ a notch and 30 ] contact surfaces (contact part) a positioning pin and 29 a connecting shaft part and 24 a plate and 19.

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[Translation done.]